



# Application of ML/AI for Calibration of Parameters of the Multigrid Beta Filter (MGBF) and its Performance within the Three-Dimensional Real-Time Mesoscale Analysis (3D RTMA) Project

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# Presentation outline

- 1. AI projects at EMC
- 2. Brief introduction into MGBF
- 3. Calibration procedure
- 4. Future extensions



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## 2. AI projects at EMC (Environmental Modeling Center)

Application of AI/ML methodology has become a very hot item in both academic and RT2O circles. NOAA's EMC was for decades a pioneer in this discipline, thanks to efforts of Dr. Vladimir Krasnopolski. From recently we started a very ambitious plan of embracing AI technology in many ongoing projects. (However, only several of those from that list are presently already funded, or we were able to incorporate them in ongoing projects.)

### Emulation (6)

[UFS short-term forecast surrogate](#)

[ML-based soil moisture](#)

[ML estimated land surface emissiv](#)

[Increase ensemble size](#)

[ML calibration of Multigrid Beta Filtr](#)

[ML-based temperature-salinity bala](#)

### Post processing (3)

[RRFS downscaling](#)

[Improve RTMA background](#)

[ML derived aviation parameters from RTMA](#)

### Observations (7)

[AMV superobs](#)

[3DRTMA observation QC](#)

[Machine Learning observatio](#)

[Aircraft observation QC](#)

[Observation anomaly detection](#)

[ML based radiance bias correction](#)

[ML/AI Approach to Converting SMAP SSS to Bulk Salinity for Data Assimilation](#)



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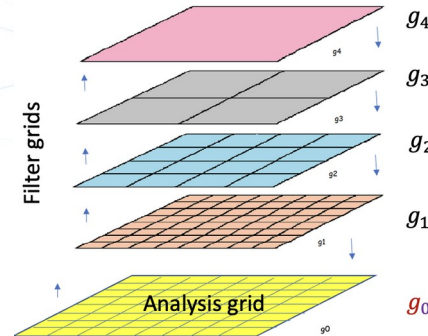
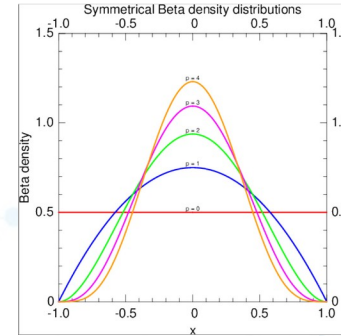
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# 1. Brief introduction into MGBF technique

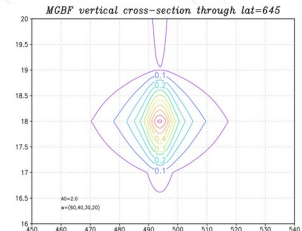
The Multigrid Beta Filter (MGBF) is a new technique for modeling of background error covariance ( $\mathbf{B}$ ), which is replacing the recursive filter (RF) as a quasi-Gaussian approximation of covariances in data assimilation at EMC.

MGBF is based on the beta distribution with a finite support and is incorporated within a parallel multigrid structure to extend the spatial coverage. That all makes it more parallelizable, which results in much better scaling.

We plan to apply AI for calibration of parameters of MGBF



Parameters of the filter that control shape and size of the covariances are: intensities of horizontal and vertical aspect tensors and scale weights in the case of 4 grid generations



### 3. Calibration procedure

We consider for now just **the homogenous and isotropic** case, in which we assume variability of covariances only in vertical direction with equal horizontal directions

Within “calibration”, we are trying to define these 6 parameters of MGBF so that resulting covariance at each level has the **shape** and **size** equal to the background covariance, as suggested by the error statistics derived using the NMC method.

The NMC method is giving us for each of 3D variables, temperature ( $\theta$ ), stream function ( $\psi$ ), velocity potential ( $\chi$ ) and moisture the average values of a characteristic scale – e-folding distance – at each of 65 model levels in both directions (  $x$  and  $y$  )

Similarly, error statistics gives us a horizontal e-folding distance ( $L_x$ ) for each of 2D variables, surface pressure sea surface, ice surface, and land surface temperatures

Technically, based on input of only 2 variables ( $L_x$ ,  $L_y$ ), it would be very hard to conclude distribution of 6 parameters of MGBF ( $L_x, L_y, L_z, \alpha_1, \alpha_2, \alpha_3$ ).

Therefore, we need to make some assumptions.

In present version of GSI, the background covariance is represented as a weighted sum of Gaussians with scaled correlation lengths defined as

$$\psi(x) = \sum_{i=1}^n \alpha_i G(x, \sigma_i L_x)$$

In version of GSI used in 3D RTMA, in vertical direction:

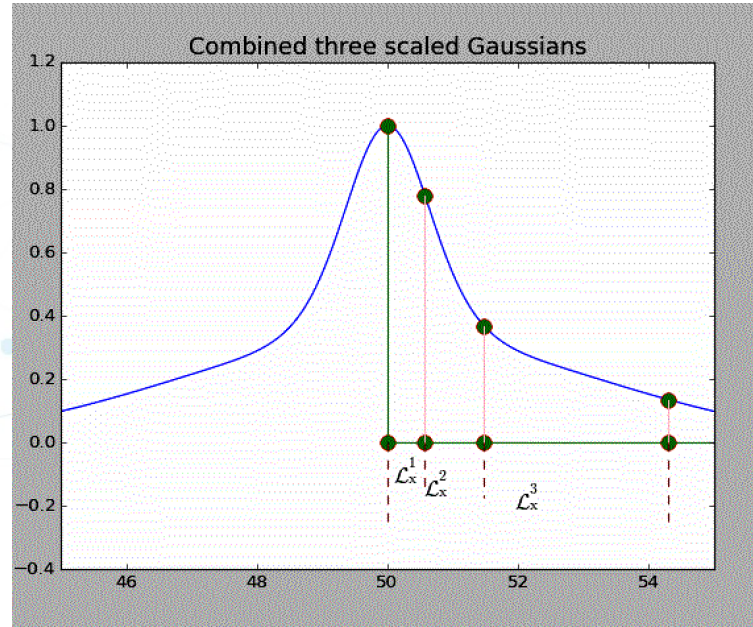
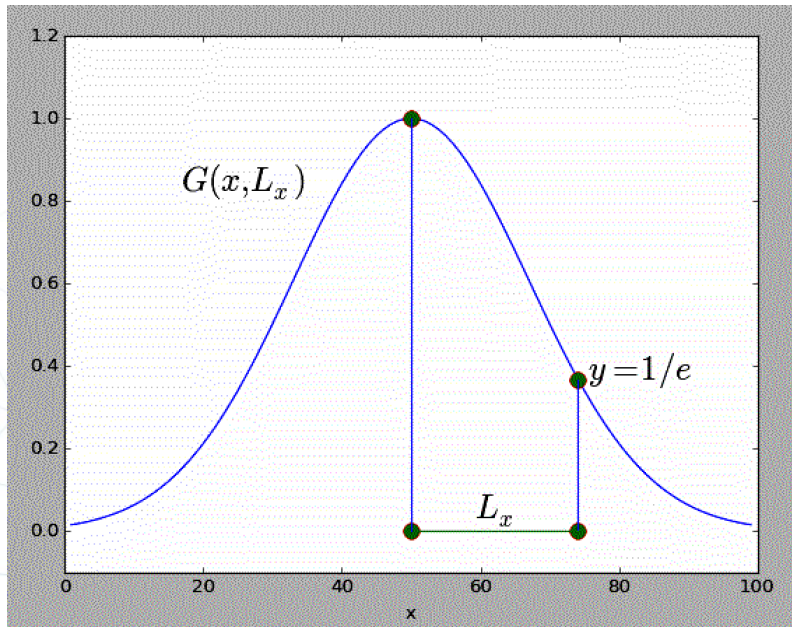
and in horizontal:

Thus, the covariances are taken to be much shorter than given correlation lengths.



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In horizontal, the derived profile (not a Gaussian any longer), can be described with not one, but three (or more) characteristic distances,, defined maybe as a half of e-folding distance, a e-folding distance and a double of it. The same procedure in the vertical direction give us three additional characteristic distances .

Thus, now we get 6 input variables to estimate 6 MGBF parameters:

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It seems that we now have enough information, but the question is how to do that!





We have found a solution in running a large series of tests with the standalone version of MGBF code

- At the **same resolution and over the domain of same size** at which GSI will be applied
- Initialize each the run with **a unit impulse** at a certain level
- Use slightly different inputs parameters ( ) in each run
- Measure the same characteristic lengths of resulting covariance in each run, that is **e-folding distance from the maximum, one half and one quarter** of it, both in horizontal and vertical directions:

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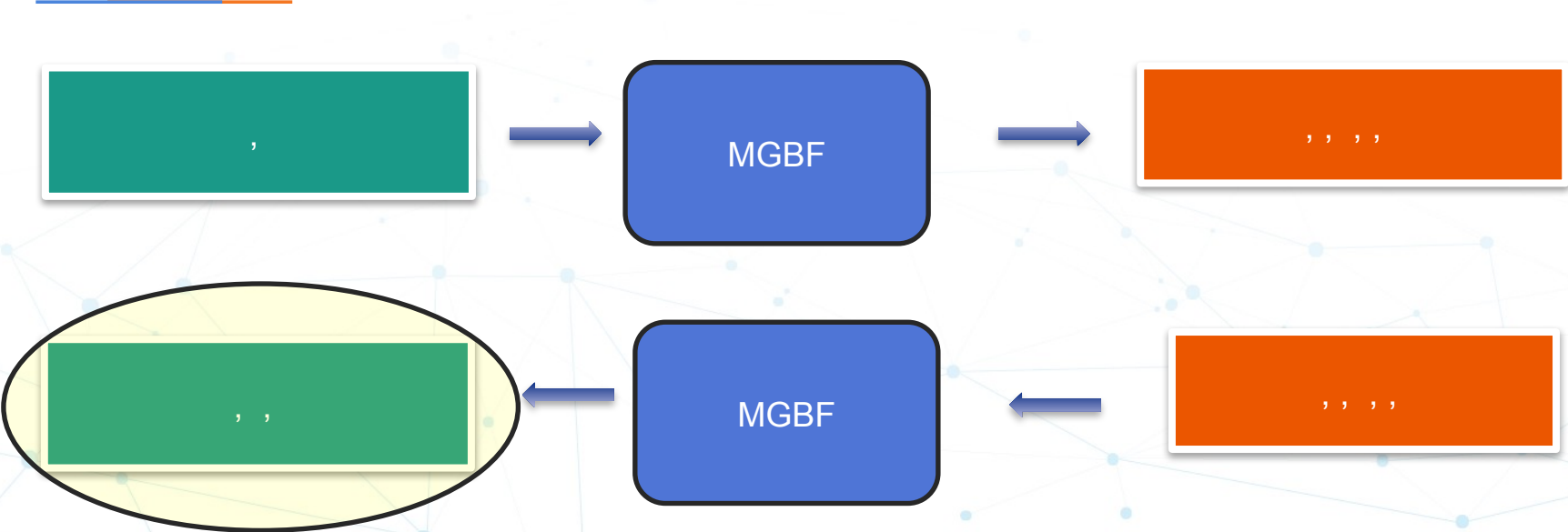
- In addition, it is important to measure the maximum value of the covariance



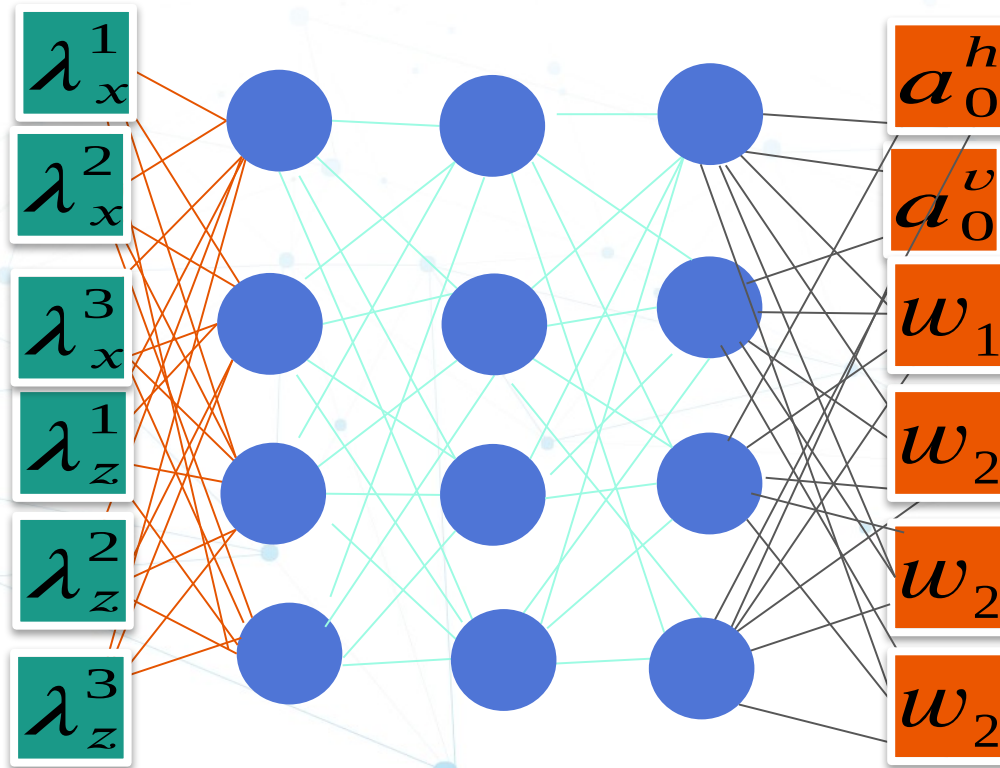
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The essence of the problem can be described with this diagram



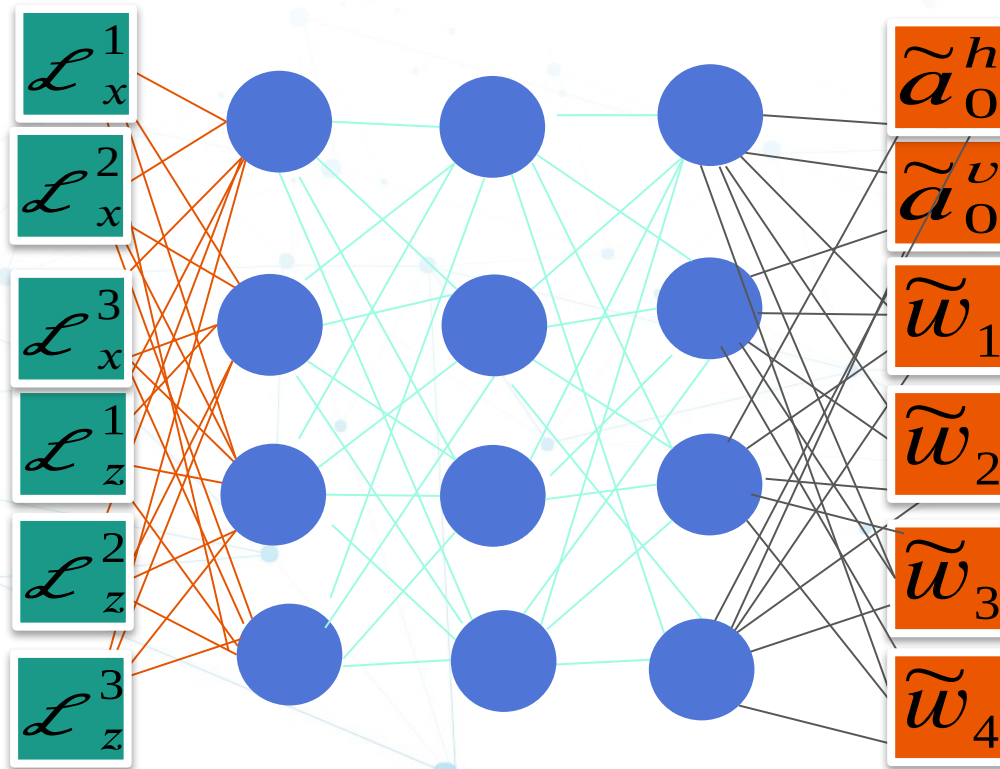
The problem could be solved by application of a **deep neural net (NN)** in which we **reorder unput and output parameters**



NN in a way emulates an inverse of MGBF by a nonlinear regression function.

We use half of data derived by running standalone version of MGBF for training (finding weights and biases of NN) and half for testing

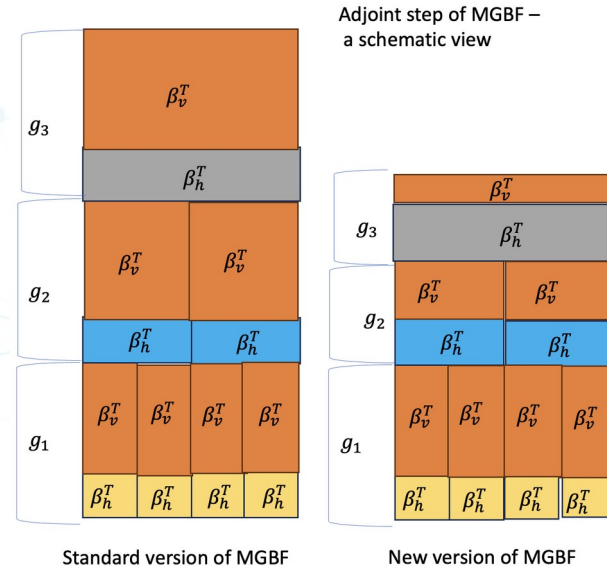
Once the NN is trained, we now use as an input correlation lengths derived from the error statistics and pick up on the output **calibrated parameters of MGBF**



In the final step, we rerun the standalone version of MGBF with derived parameters, find maximum values of covariances, and divide by it derived scale weights, which will ensure that in GSI we get normalized covariances

## 4. Future Extensions

- In order to take full advantage of the described method, a new version of MGBF was developed to improve efficiency of filtering in vertical direction where we encountered very long covariances
- This was done by reducing vertical resolution of higher grid generation, which in a way mimics horizontal application of multigrid
- We are developing an upgrade of this version in which horizontal and vertical filter will be better separated, which will improve versatility of the described calibration procedure



- One limitation of the described method is assumption about the shape of the covariance that we made based on correlation length derived by the NMC method
- We are looking into various ways how to get more useful information directly from error statistics of the background field without making such assumptions



Thank you for your attention!  
Stay safe and healthy!



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